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*РУСЕНСКИ УНИВЕРСИТЕТ "АНГЕЛ КЪНЧЕВ"
СЪЮЗ НА УЧЕНИТЕ - РУСЕ*



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**SESSIONS SCHEDULE & ABSTRACTS
ПРОГРАМА & РЕЗЮМЕТА**

**2017
BULGARIA
Ruse
Razgrad
Silistra**

	Natasha Vakiyeva-Bancheva, Rayka Vladova, Elisaveta Georgieva Kirilova
FRI-2.209-1-EC-03:	Features of climate change and the impact on the functioning of the agro-industrial complex south-east of Kazakhstan Suleimenova N. Sh, Margarita Filipova, Kalikov D. B
FRI-2.209-1-EC-04:	Soil contamination by heavy metals in the application mineral fertilizers in the irrigated zones of Kazakhstan Suleimenova N. Sh, Mahamedova B. Y, Margarita Filipova, Kuandikova E. M
FRI-2.209-1-EC-05:	Analysis of environmental criticality Lyubomir Vladimirov
FRI-2.209-1-EC-06:	The risk of cross-border smuggling of radioactive materials Stefko Burdjiev
FRI-2.209-1-EC-07:	The modular underwater – bottom installation for semi-extensive growing of bivalves Plamen Manev, Anton Antonov
FRI-2.209-1-EC-08:	Motivation of the students-ecologists in training for their specialty Daniela Hristova
FRI-2.209-1-EC-09:	Study of the noise, generated from different car's tyres Nikolay Kovachev

14:00-16:00

Parallel Sessions Room 16.203

FRI-16.203-1-ID

Industrial Design
Session Chair: Cvetomir Konov

FRI-16.203-1-ID-01:

Geometric heuristics in art end design
Boryana Georgieva

FRI-16.203-1-ID-02:

Becoming the most successful world fashion blog: analysis, problems, technology and solutions
Stoyan Bundjulov

FRI-16.203-1-ID-03:

Materials for model and mock-up activity
Cvetomir D. Konov

FRI-16.203-1-ID-04:

A three-dimensional representation of semantic circle
Petya Boneva

14:00-16:00

Parallel Sessions Room 1.417

FRI-1.417-1-MEMBT

Mechanical Engineering and Machine-building Technologies
Session Chair: Rusi Minev

FRI-1.417-1-MEMBT-01:

Design developments of vibration-driven mobile robots
Ivan Loukanov, Venko Vitliemov, Svetlın Stoyanov, Stoyan Stoyanov

FRI-1.417-1-MEMBT-02:

Determination of joint angles of bipedal robot using forward and inverse kinematics and zero moment point models
Taşkın Tez, Hilmi Kuşçu

FRI-1.417-1-MEMBT-03:

Investigation of wear properties and strength of polymeric materials used in tension pulleys which is reinforced with glass fiber and glass bead
Nurşen Öntürk, Osman Yeşen, Sencer Karabeyoğlu

FRI-1.417-1-MEMBT-04:

Investigation of properties of thermoplastic composite layers supported by organic and inorganic materials
Sencer Karabeyoğlu, Olcay Ekşi

DETERMINATION OF JOINT ANGLES OF BIPEDAL ROBOT USING FORWARD AND INVERSE KINEMATICS AND ZERO MOMENT POINT MODELS

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Abstract: In recent years, robotics studies have gained great momentum in industry, medicine, education, agriculture, and in all areas of life along with rapid developments in electronics, computers, and control technology. With the increase in robotic studies, the walking of biped robots has increasingly become similar to that of human. Compared to other living creatures in nature, walking on two legs is one of the most important features of man. For this reason, this study aims to calculate joint angles of a bipedal robot using forward and inverse kinematics to imitate human-like walking. In this study, 12 state-of-the-art intelligent servo motors are used to make a bipedal robot.

Keywords: Bipedal Robot, Servo Control, Forward and Inverse Kinematics, Zero Moment Point.

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FRI-1417-1-MEMBT-03

INVESTIGATION OF WEAR PROPERTIES AND STRENGTH OF POLYMERIC MATERIALS USED IN TENSION PULLEYS WHICH IS REINFORCED WITH GLASSFIBER AND GLASS BEAD

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Abstract: In this study, materials which are used in plastic pulleys of the tension rollers is investigated. The materials for tension pulleys have produced by using various polymers (POM, PE, and PA6.6) and material reinforcements (glass fiber and glass bead). Special abrasion test machines have assayed these produced tension pulleys. In these test machines, pulleys abrasion values have obtained on a stable temperature at varied loads. Mechanical and physical tests are also applied to the produced composite materials. In the light of obtained data, high wear resistance and durability are aimed.

Keywords: Tension Roller, Composite Materials, Pulley abrasion.